



SE-7385

B. E. IV (ECC) (Sem. VII) Examination

May / June – 2011

Electronics System Design

Time : Hours]

[Total Marks : 100

Instructions :

(1)

नीचे दशांशिक निशानीवाणी विगतो उत्तरवही पर अवश्य कभवी. Fillup strictly the details of signs on your answer book.	Seat No. : □ □ □ □ □ □
Name of the Examination : B. E. - IV (ECC) (Sem. VII)	Student's Signature
Name of the Subject : Electronics System Design	
Subject Code No. : 7 3 8 5 Section No. (1, 2,.....) : 1, 2	

- (2) Attempt all questions.
- (3) Figures to the right indicate full marks.
- (4) Assume suitable data whenever necessary and specify your assumptions clearly.
- (5) use of scientific non-programmable calculator CASIO Fx 82, 83, 100 or equivalent of other makes is allowed.

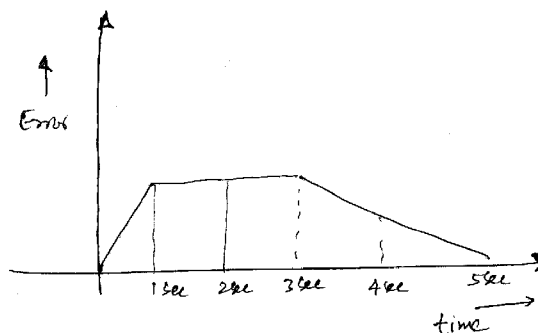
SECTION - I

- 1 Do as directed. 20
 - (i) Draw ideal transfer curve of voltage regulator. 2
Justify the shape.
 - (ii) Larger the value of K_p (Proportional mode controller constant), less value of error is required to saturate controller output. True or False ? Justify your answer. 2
 - (iii) List units of integral mode controller constant and derivative mode controller constant, with its significance. 2
 - (iv) Load current carrying capacity of fold back circuit is lower compared to simple short circuit protection for same series pass device. True or False ? Justify your answer. 2
 - (v) The temperature has a range of 300K to 440K and a set point of 380K. Find the percentage of span error when measured temperature is 375K. 2
 - (vi) Power consumption in linear voltage regulator is higher compared to switch mode power supply. True or false ? Justify your answer. 2
 - (vii) Define following in context of process and control characteristics. 6
 - (1) process equation (2) Dead time (3) process lag

- (viii) Higher the value of filter capacitor, higher the value of ripple factor. True or false ? Justify your answer. 2
- 2 (a) How fold back current limiting can be treated as improved version of constant current limiting ? 7
- (b) With the help of waveforms and diagram explain operation of buck type switching regulators; derive design equations and subsequently design regulator for output rating $V_0=10V$, $I_0=4A$ and output ripple=200mV. Input voltage = 30 V and switching frequency for SMPS to be 45KHz. 8

OR

- 2 (a) It is expected to design voltage regulator circuit with a linear fold back characteristics that goes to a current limit of 20A at regulated output $V_0=10V$, and has short circuit limit of 7A. The unregulated input voltage has maximum value of 30V. 8
- (i) Draw output voltage versus output current.
- (ii) Determine parameter of the linear fold back network.
- (iii) Find the max power rating of the output transistor.
- (iv) Find the output voltage and the output current at which the max power dissipation occurs.
- (b) Describe operating principle of switch mode power supply, clearly justify how it regulates voltage against variation in supply voltage and load current. Draw buck and boost configuration of SMPs. 7
- 3 (a) What do you mean by speed in float type controller? Differentiate single speed and multi speed float controllers. 5
- (b) Derive controller output for following error profile, if controller is of PD type and having parameters $K_d=0.4s$ (D Mode), $K_p = 5$ (P Mode) and $P_o = 15\%$. Draw graph of controller output based on values of controller output. Desing and draw circuit of the controller. 5



- (c) It is required to design two position controller with following data : 5
- For upper value of temperature: Switch off relay at 75 degrees and switch on 70 degrees for lower value of voltage : Switch off relay at 35 degrees and switch on degrees. Assume suitable scale factors for sensing speed. Explain each design steps and derive expressions you use.

SECTION - II

- 4 (a) Answer the followings : 12
- (i) State functions of EA' and PSEN' pins of 8051.
 - (ii) Explain the immediate addressing mode w.r.t.MOV instruction ?
 - (iii) State timer roll over value for mode 1 and 2.
 - (iv) What do you mean by simplex, full duplex and half duplex communication ?
 - (v) State vector locations for external hardware interrupts of 8051.
 - (vi) To interface external memory with 8051 which ports provide address and data line ? How ?
- (b) Explain following 8051 instructions with suitable example. 04
- (i) DIV AB (ii) RR A
- (c) Explain indirect memory addressing modes in 8051 w.r.t. MOV instructions. 04
- 5 (a) Write a program to get hex data in the range of 00-FFH from PORT1 and convert it to decimal as unpacked BCD. Save the BCD digits in R7, R6 and R5 registers. 05
- (b) Write a program to generate square wave with 75% duty cycle on pin P0.5. What precaution is required while using 8051 ports as input ports ? 06
- (c) State steps of programming using polling method to program timers of 8051 in mode 2. 04

OR

- 5 (a) Assume internal RAM memory locations 40-44H contains data. Search to see if any of the values equals 65H. If value 65H does exist, give the location of first searched byte to R4; otherwise make R4-00H. **05**
- (b) What is difference between the RET and RETI instruction ? Explain why we can not use RET instead of RETI as the last instruction of an ISR ? **06**
- (c) With the help of diagram explain how to program external hardware interrupts of 8051 ? **04**
- 6 Attempt any three. **15**
- (a) Write a program to generate a 5ms pulse using timer 1. Take 12 MHz crystal frequency and neglect instruction overhead. Output square wave on pin p3.2.
- (b) With the help of block diagram show how to connect PC serial with 8051. Also indicate baud rates supported by IBM PC.
- (c) Explain function of SBUF and SCON registers for serial port programming.
- (d) Give the interfacing of ADC 0809 with microcontroller 8051. Also write a program to read analog input and display the result in A.
- (e) Explain interfacing of matrix keyboard with 8051 micro controller.
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